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Aberration retrieval for high-NA optical systems using the Extended Nijboer-Zernike theory

P. Dirksen¹, J. Braat^{2,3}, A. Janssen³ and A. Leeuwestein³

1) Philips Research Leuven, Belgium

2) Technical University of Delft, Delft, The Netherlands

3) Philips Research Eindhoven, The Netherlands

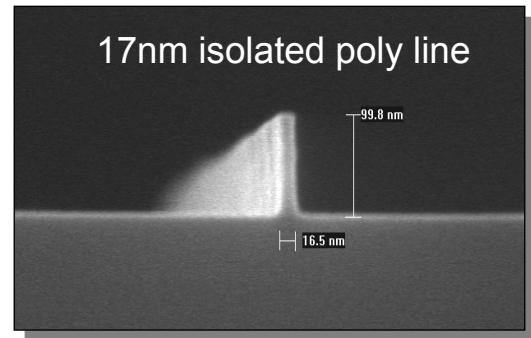
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Overview

- Introduction
- Review low-NA ENZ-Theory
 - Retrieval of aberrations and image blur parameters
- High-NA ENZ-Theory
- Validating high-NA formulas
- Experimental high-NA retrieval results

Introduction



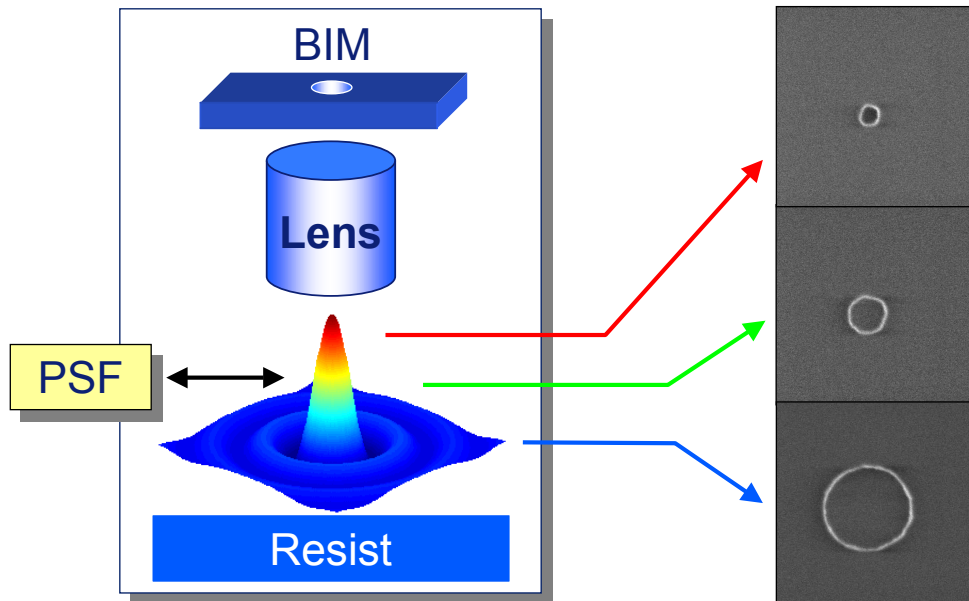
- Trend:
 - High resolution, tight CD budgets
 - Very high-NA optical system
 - Increasing impact of aberrations and image blur

Introduction: aberrations and blur

- Aberrations of the projection optics
 - e.g. spherical, coma and transmission errors
- Image blur:
 - In the horizontal plane: acid diffusion, stage noise,...
 - In the vertical plane: focus noise caused by chromatic aberrations combined with laser bandwidth,...
- This presentation discusses the pinhole experiment to retrieve aberrations and image blur parameters for high-NA optical systems

Introduction: pinhole experiment

Reconstruct intensity PSF from top-down SEM images



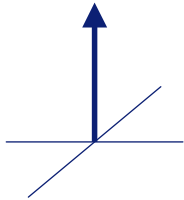
Introduction: through-focus PSF



How to retrieve aberrations and image blur parameters from a through-focus intensity PSF for a high-NA system ?

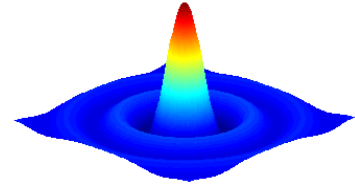
The key: ENZ theory

δ - function



Lithographic lens,
microscope or
EUV Mirror system

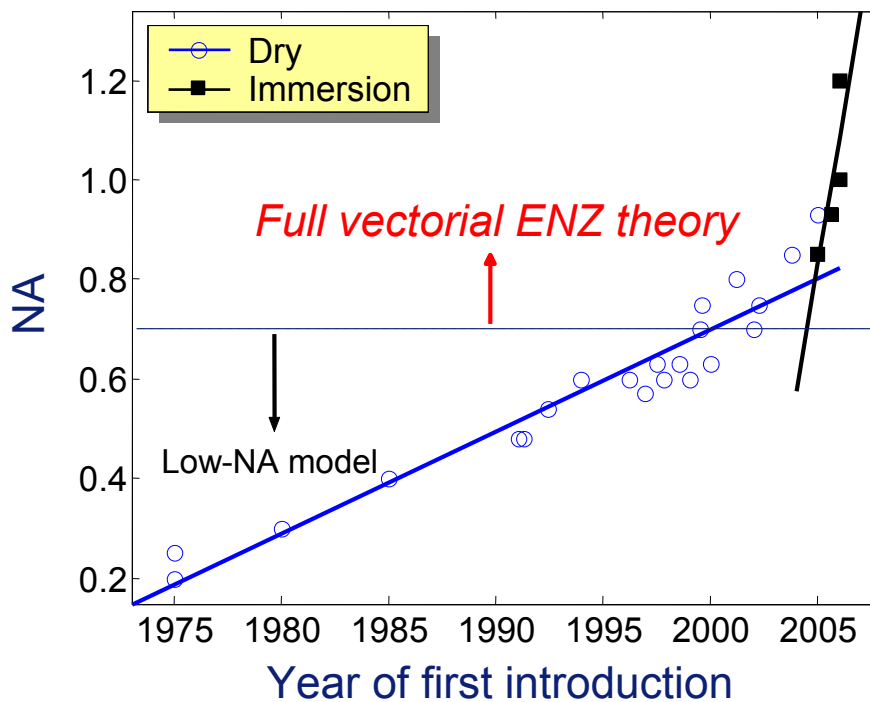
PSF



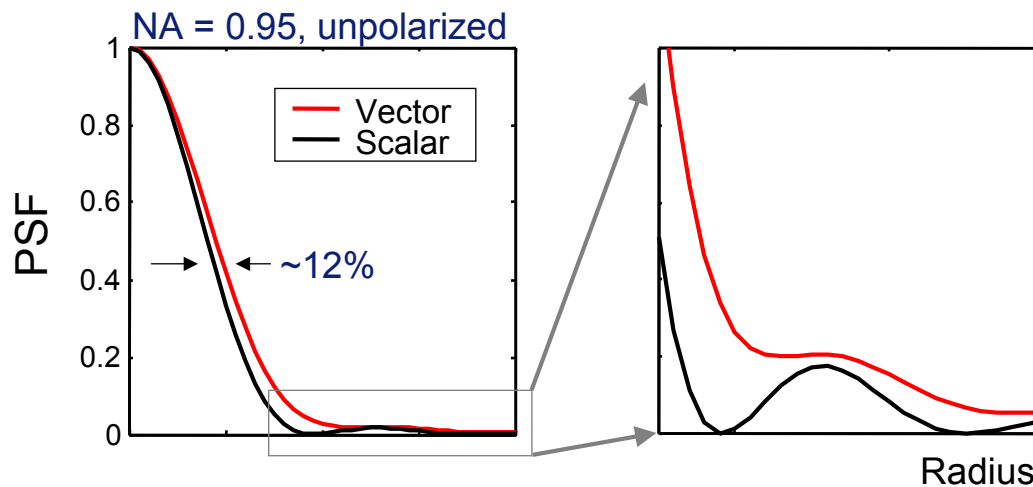
The high-NA Extended Nijboer-Zernike (ENZ) theory provides an analytical description of the PSF

The theory allows the retrieval of aberrations and image blur parameters from the measured intensity PSF

Introduction: evolution of NA



Introduction: scalar versus vector



- For $NA > 0.70$:
 - Low-NA retrieval provides reduced accuracy
 - Low-NA overestimates image blur parameters
- Vector model needed

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It started with the 1942 thesis of Nijboer...

THE DIFFRACTION THEORY OF ABERRATIONS

PROEFSCHRIFT

TER VERKRIJGING VAN DEN GRAAD VAN DOCTOR IN DE WIS- EN NATUURKUNDE AAN DER LIKS-UNIVERSITEIT TE GRONINGEN, OP GEZAG VAN DEN RECTOR MAGNIFICUS DR. J. M. N. KAPTEYN, HOOGLEERAAR IN DE FACULTEIT DER LETTEREN EN WISBEGEERTE, TEGEN DE BEDENKINGEN VAN DE FACULTEIT DER WIS- EN NATUURKUNDE TE VERDEDIGEN OP MAANDAG 1 JUNI 1942, DES NAMIDDAGS OM 4.15 UUR PRECIJS

DOOR

BERNARD ROELOF ANDRIES NIJBOER
 GEBOREN TE MEPPEL

E-field = Airy + Zernike • aberrations

$$U(r, \varphi) \approx 2 \frac{J_1(r)}{r} + 2 \sum_{n,m} i^{m+1} \alpha_{nm} \frac{J_{n+1}(r)}{r} \cos(m\varphi)$$

- Best focus, small aberrations
- Defocus included for a few low order terms only

Low-NA Extended Nijboer-Zernike theory (2002)

$$U(r, \varphi, f) \approx 2V_{00}(r, f) + 2 \sum_{nm} \alpha_{nm} i^{m+1} V_{nm}(r, f) \cos(m\varphi)$$

- The basis for aberration retrieval
- $V_{nm}(r, f)$ have a convenient Bessel series representation with nice symmetry and orthogonality properties
- The old theories (Airy, Lommel and Nijboer-Zernike) arise as special cases

Low-NA aberration retrieval

$$I(r, \varphi, f) \approx I_{0,0}(r, f) + \sum_{n,m} \alpha_{n,m} [\text{Aberration terms}]$$

- Best match between experimental intensity PSF $I(r, \varphi, f)$ and theoretical expression
- α_{nm} are found by solving a system of linear equations
- *Details are given in this conference paper*

Additions to low-NA ENZ theory

In the period 2002-2004, various additions were made:

- Retrieval of phase and transmission errors
- Finite pinhole size is taken into account
- Image blur caused by stochastic variation of (x,y,z), retrieval of image blur parameters
- Large defocus
- Retrieval of large aberrations by iterative procedure

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From low-NA to high-NA ENZ (2003)

Scalar: $U(r, \phi, f) = 2V_{00} + 2 \sum_{nm} \alpha_{nm} i^{m+1} V_{nm} \cos(m\phi)$



Electric field vector for X-polarized illumination

$$\mathbf{E}^x(r, \phi, f) = -i\gamma s_0^2 \exp\left(\frac{-if}{u_0}\right) \sum_{n,m} i^m \beta_{nm}^x \exp(im\phi) \begin{pmatrix} V_{nm,0} + \frac{s_0^2}{2} V_{nm,2} \exp(2i\phi) + \frac{s_0^2}{2} V_{nm,-2} \exp(-2i\phi) \\ -\frac{is_0^2}{2} V_{nm,2} \exp(2i\phi) + \frac{is_0^2}{2} V_{nm,-2} \exp(-2i\phi) \\ -is_0 V_{nm,1} \exp(i\phi) + is_0 V_{nm,-1} \exp(-i\phi) \end{pmatrix}$$

Polarization dependent aberrations

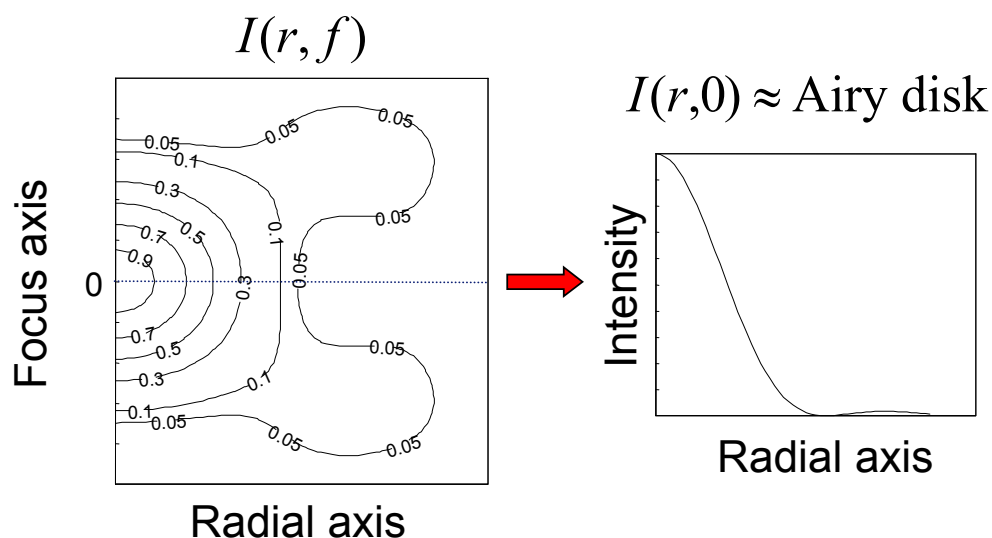


$V_{nm,j}$ is expressible in terms of the 'old'- V_{nm} functions

A significant increase in complexity, however ...

- This presentation: unpolarized illumination case
 - A simplification occurs and the retrieval scheme strongly resembles the low-NA scheme. The various additions can also be made for the high-NA case
 - Second simplification: analysis limited to the case of rotationally symmetrical terms
- *General, polarized case is presented elsewhere*

Display through-focus intensity PSF



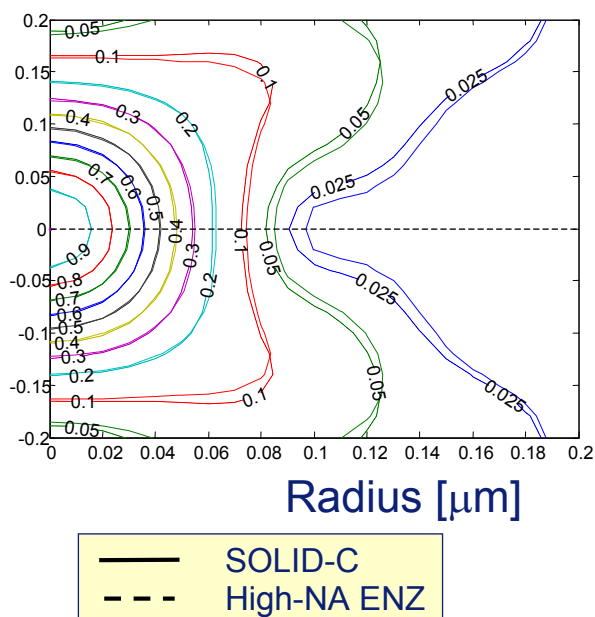
Validation forward calculation

- First we validate the forward high-NA ENZ calculation by comparing the ENZ results to results obtained from a lithographic simulator (SOLID-C)

SPIE 5754-26, March 2, 2005, San Jose, CA

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Validating forward calculation



Example: wet, NA=1.35, $\lambda=193$

Other cases (not shown):

- Finite pin hole size
- Aberrations
- Diffusion
- Focus noise

**In all cases a good agreement with the simulator was found:
Max |error| < 1.5%**

SPIE 5754-26, March 2, 2005, San Jose, CA

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Retrieval at high NA

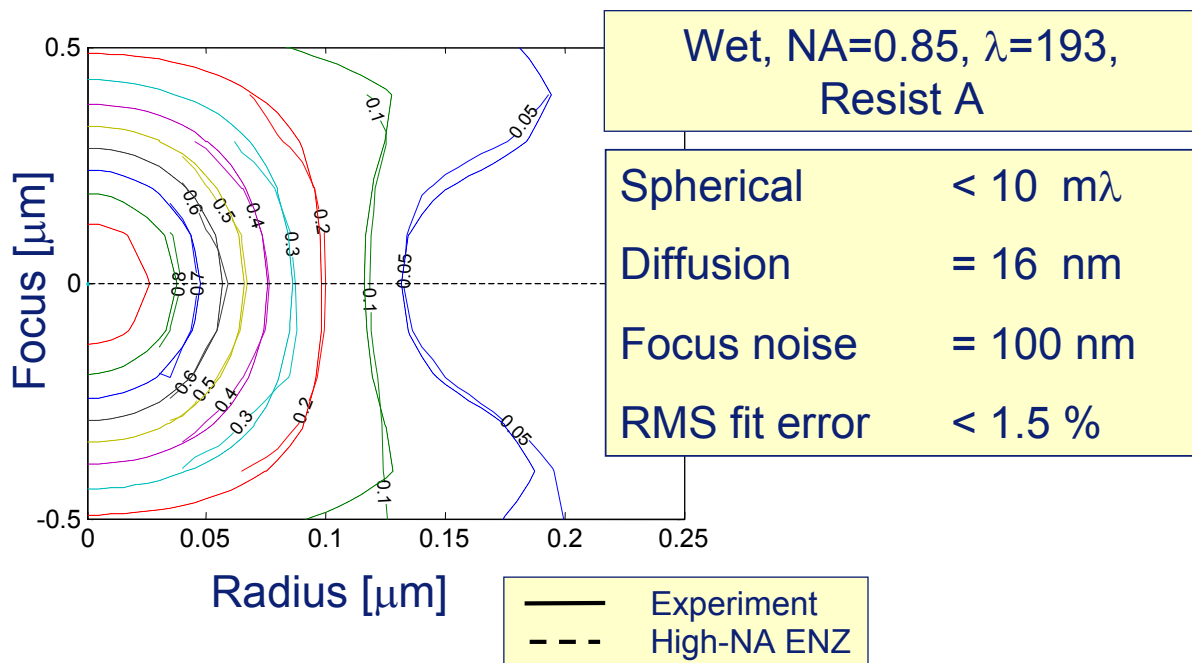
- The basic concept: the measured intensity PSF is matched to the intensity from the high NA ENZ-theory
- For an unpolarized system: a similar retrieval scheme as the low-NA case exists
- Solving a system of linear equations. The retrieval procedure estimates the aberrations as well as the image blur parameters (diffusion and focus noise)
- *Details are given in this conference paper*

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High-NA retrieval, immersion

Experimental data pinhole experiment



High-NA retrieval, dry

Experimental data pinhole experiment

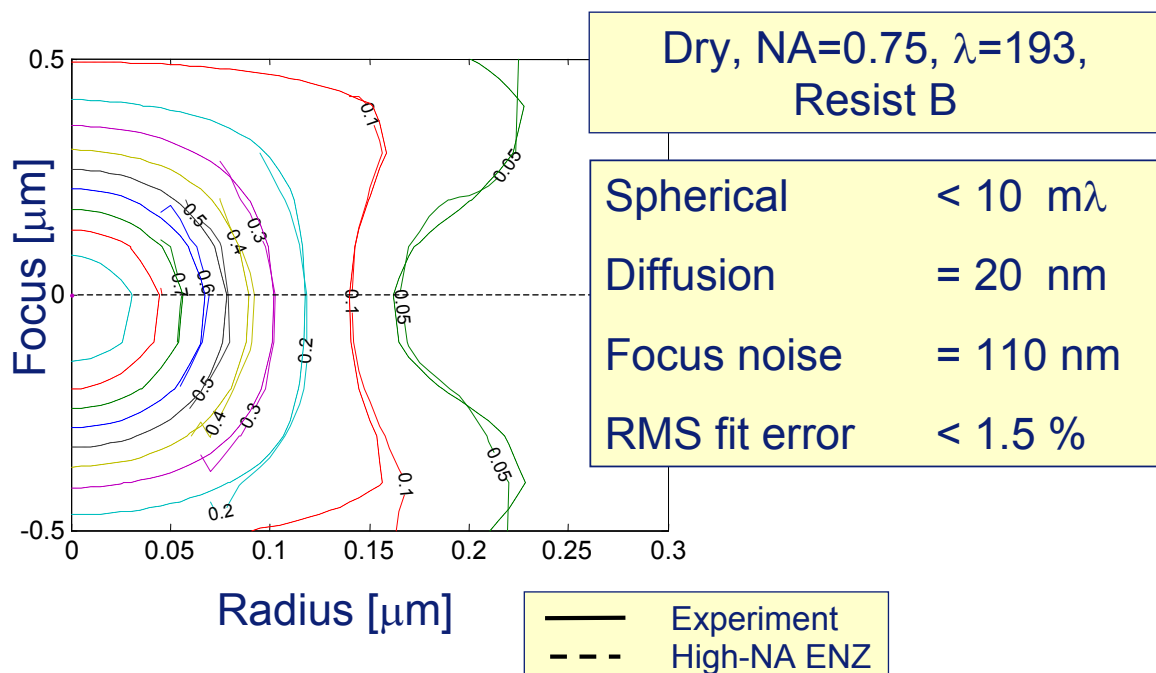


Image blur and PEB time (1)

Impact Post Exposure Bake (PEB) time:

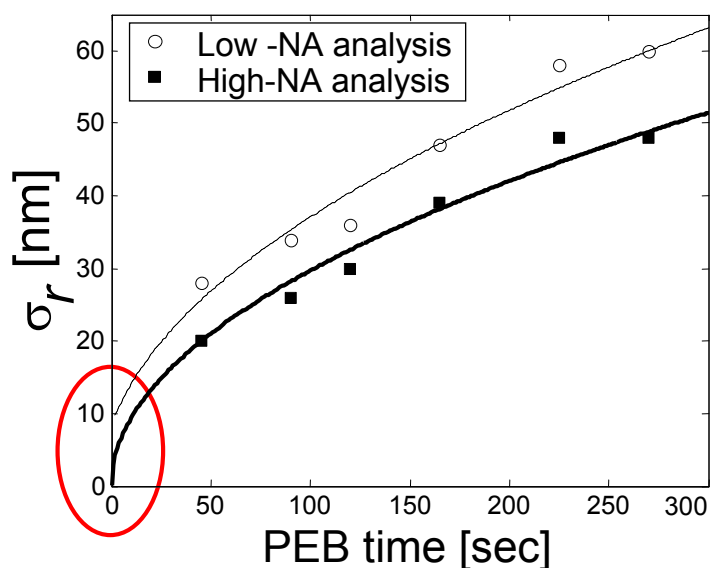
- A simple Fickian diffusion model predicts an increase in diffusion length with time:

$$\sigma_r = \sqrt{D \cdot t}$$

- Experiments shown on previous sheet repeated for various PEB times

Image blur and PEB time (2)

Resist B, Dry, NA=0.75, $\lambda=193$



$$\sigma_r = \sqrt{D \cdot t + \text{offset}}$$

10 nm offset found with low NA model: of the order of the diffusion length

⇒ High-NA model required for accuracy

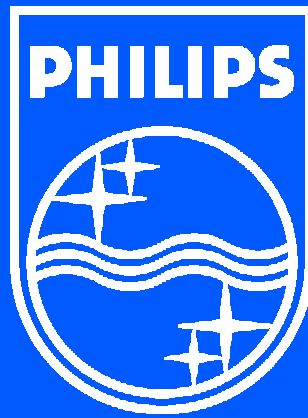
Summary

- The *inverse problem* of retrieving aberrations and image blur parameters from the intensity PSF, is solved by using the high-NA ENZ approach
- High-NA model needed if $NA > 0.70$
- High-NA model was validated, good agreement between experiment, theory and numerical simulations
- Method also applies to immersion systems

Acknowledgement

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- Philips Research Leuven makes use of the cleanroom facilities of IMEC

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Additional slides ...

The key: match measured and theoretical Fourier components

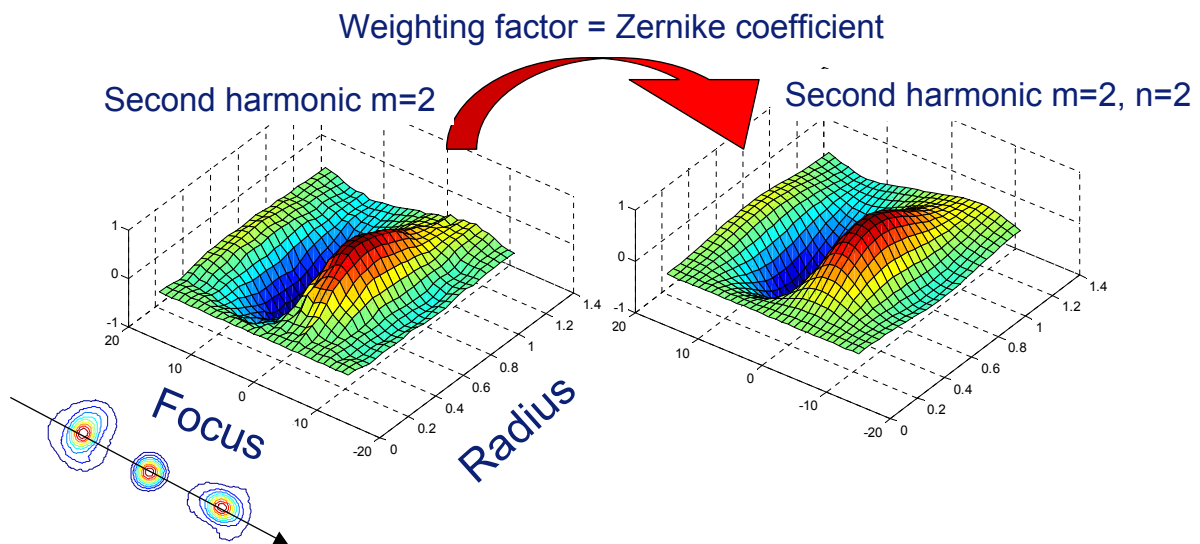
Fourier analysis of the through-focus PSF: splits according to azimuthal order and suppresses noise.

$$\psi^m = \frac{1}{2\pi} \int_0^{2\pi} I(r, \varphi, f) \cos(m\varphi) d\varphi$$

- m=0: Spherical + aberration-free
- m=1: Coma
- m=2; Astigmatism
- Etc ...

Retrieval example: astigmatism

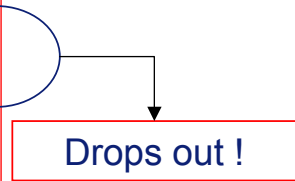
Match experimental $\psi^{m=2}(r, f)$ to theoretical $\psi_{n=2}^{m=2}(r, f)$



Some details on aberration retrieval

$$U(r, \varphi, f) \approx 2V_{00} + 2 \sum_{nm} \alpha_{nm} i^{m+1} V_{nm} \cos(m\varphi),$$

$$I(r, \varphi, f) \approx 4|V_{00}|^2 + 8 \sum_{nm} \alpha_{nm} \operatorname{Re}\{i^{m+1} V_{00}^* V_{nm}\} \cos(m\varphi) + \dots$$



$\psi^m = m^{\text{th}}$ - Fourier component of $I(r, \varphi, f)$

$$\psi^m = \sum_n \alpha_{nm} \psi_n^m \quad \text{with} \quad \psi_n^m = 4 \operatorname{Re}\{i^{m+1} V_{00}^* V_{nm}\}$$

Take inner products :

$$(\psi^m, \psi_{n'}^m) = \sum_n \alpha_{nm} (\psi_n^m, \psi_{n'}^m) \longrightarrow \text{a linear system of equations.}$$

Aberration retrieval & noise

m^{th} - Fourier component

basic intensity functions

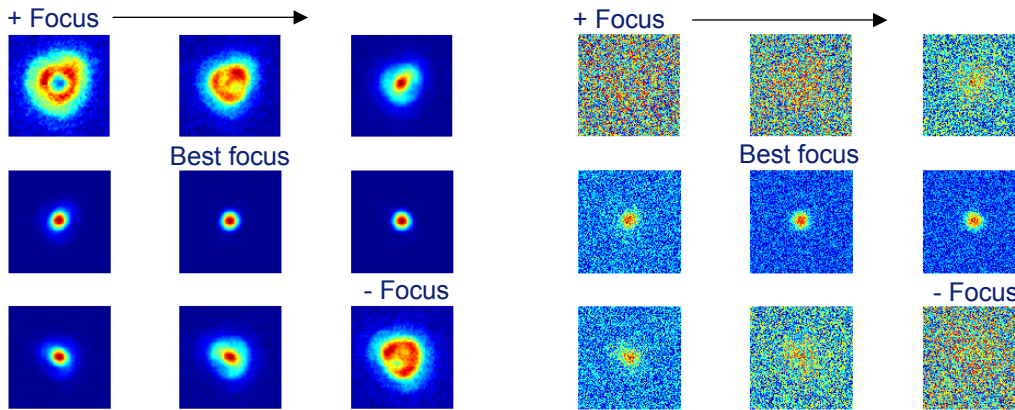
$$\psi^m = \sum_n \alpha_{nm} \psi_n^m \quad \text{with} \quad \psi_n^m = 4 \operatorname{Re}\{i^{m+1} V_{00}^* V_{nm}\}$$

↑
Aberration parameter

Match experimental frequency component (ψ^m) to specific through-focus signatures (ψ_n^m). The ψ_n^m are (close to being) orthogonal.

- ◆ Aberration retrieval is *noise insensitive*
- ◆ Be careful with DC-intensity offset

Example: impact noise



Small change in retrieved aberration coefficients: $\Delta Z \sim 10 \text{ m}\lambda$

Validating image blur formulas

No diffusion

40 nm diffusion

NA=0.85, $\lambda=193$

NA=0.85, $\lambda=193$

